Collapsed Variational Inference for Sum-Product Networks

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Sum-Product Networks

Definition

A Sum-Product Network (SPN) is a

- Rooted directed acyclic graph of univariate distributions, sum nodes and product nodes.
- ► Value of a product node is the product of its children.
- Value of a sum node is the weighted sum of its children, where the weights are nonnegative.
- Value of the network is the value at the root.



Sum-Product Networks

Mixture of Trees

Each SPN can be decomposed as a mixture of trees:



- Each tree is a product of univariate distributions.
- Number of mixture components is Ω(2^{Depth}).
- Each network computes a positive polynomial (posynomial) function of model parameters:

$$V_{\text{root}}(\mathbf{x} \mid \mathbf{w}) = \sum_{t=1}^{\tau_{S}} \prod_{(k,j) \in \mathcal{T}_{tE}} w_{kj} \prod_{i=1}^{n} p_{t}(X_{i} = \mathbf{x}_{i})$$

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Sum-Product Networks

Bayesian Network

Alternatively, each SPN ${\cal S}$ is equivalent to a Bayesian network ${\cal B}$ with bipartite structure.



- Number of sum nodes in S = Number of hidden variables in B = Θ(|S|). |B| = O(n|S|)
- ► Number of observable variables in B = Number of variables modeled by S.
- Typically number of hidden variables >> number of observable variables.
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Variational Inference

Brief Introduction

Bayesian Inference:



Often intractable because of:

- No analytical solution.
- Expensive numerical integration.

General idea: find the best approximation in a tractable family of distributions Q:

minimize_{$$q \in Q$$} KL[$q(\mathbf{w}) \parallel p(\mathbf{w} \mid \mathbf{x})$]

Typical choice of approximation families: Mean-field, structured mean-field, etc. Carnegie Mellon University

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Variational Inference

Brief Introduction

Variational method: Optimization-based, deterministic approach for approximate Bayesian inference.

$$\inf_{q \in Q} \mathsf{KL}[q(\mathbf{w}) \mid\mid p(\mathbf{w} \mid \mathbf{x})] \Leftrightarrow \sup_{q \in Q} \mathbb{E}_q[\log p(\mathbf{w}, \mathbf{x})] + \mathbb{H}[q]$$

Evidence Lower Bound $\widehat{\mathcal{L}}$:

$$\log p(\mathbf{x}) \geq \sup_{q \in Q} \mathbb{E}_q[\log p(\mathbf{w}, \mathbf{x})] + \mathbb{H}[q] =: \widehat{\mathcal{L}}$$

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Motivations and Challenges

Bayesian inference algorithms for SPNs:

- Flexible at incorporating prior knowledge about the structure of SPNs.
- More robust to overfitting.

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Motivations and Challenges



- ► W Model parameters, global hidden variables.
- H Assignments of sum nodes, local hidden variables.
- ► X Observable variables.
- ► *D* Number of instances.

Challenges for standard VB:

► Large number of local hidden variables: number of local hidden variables = Number of sum nodes = Θ(|S|).

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- Memory overhead: space complexity O(D|S|).

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Challenges for standard VB:

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- Memory overhead: space complexity O(D|S|).
- Time complexity: O(nD|S|).

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Contributions

Our contributions:

- ► We obtain better ELBO L to optimize than L, the one obtained by mean-field.
- ► Reduced space complexity: O(D|S|) ⇒ O(|S|), space complexity is independent of training size.
- ► Reduced time complexity: O(nD|S|) ⇒ O(D|S|), removing the explicit dependency on the dimension.

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Efficient Marginalization

Recall ELBO in standard VI:

$$\widehat{\mathcal{L}} \mathrel{\mathop:}= \mathbb{E}_{q(\mathbf{w},\mathbf{h})}[\log p(\mathbf{w},\mathbf{h},\mathbf{x})] + \mathbb{H}[q(\mathbf{w},\mathbf{h})]$$

Consider the new ELBO in Collapsed VI:

$$\begin{split} \mathcal{L} &:= \mathbb{E}_{q(\mathbf{w})}[\log p(\mathbf{w}, \mathbf{x})] + \mathbb{H}[q(\mathbf{w})] \\ &= \mathbb{E}_{q(\mathbf{w})}[\log \sum_{\mathbf{h}} p(\mathbf{w}, \mathbf{h}, \mathbf{x})] + \mathbb{H}[q(\mathbf{w})] \end{split}$$

We can establish the following inequality:

$$\log p(\mathbf{x}) \geq \mathcal{L} \geq \widehat{\mathcal{L}}$$

The new ELBO in Collapsed VI leads to a better lower bound than the one used in standard VI! Carnegie Mellon University

Comparisons

Standard Variational Inference

Mean-field assumption: $q(\mathbf{w}, \mathbf{h}) = \prod_i q(w_i) \prod_j q(h_j)$ ELBO: $\widehat{\mathcal{L}} := \mathbb{E}_{q(\mathbf{w}, \mathbf{h})}[\log p(\mathbf{w}, \mathbf{h}, \mathbf{x})] + \mathbb{H}[q(\mathbf{w}, \mathbf{h})]$

Collapsed Variational Inference for LDA, HDP

Collapsed out global hidden variables: $q(\mathbf{h}) = \int_{\mathbf{w}} q(\mathbf{w}, \mathbf{h}) d\mathbf{w}$ ELBO: $\mathcal{L}_{\mathbf{h}} := \mathbb{E}_{q(\mathbf{h})}[\log p(\mathbf{h}, \mathbf{x})] + \mathbb{H}[q(\mathbf{h})]$ Better lower bound: $\mathcal{L}_{\mathbf{h}} \ge \widehat{\mathcal{L}}$

Collapsed Variational Inference for SPN

Collapsed out local hidden variables: $q(\mathbf{w}) = \sum_{\mathbf{h}} q(\mathbf{w}, \mathbf{h})$ ELBO: $\mathcal{L}_{\mathbf{w}} := \mathbb{E}_{q(\mathbf{w})}[\log p(\mathbf{w}, \mathbf{x})] + \mathbb{H}[q(\mathbf{w})]$ Better lower bound: $\mathcal{L}_{\mathbf{w}} \geq \widehat{\mathcal{L}}$

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Efficient Marginalization

Time complexity of the exact marginalization incurred in computing $\sum_{\mathbf{h}} p(\mathbf{w}, \mathbf{h}, \mathbf{x})$:

► Time complexity of marginalization in graphical model G: O(D · 2^{tw(G)}).

Space complexity reduction:

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Efficient Marginalization

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- ► Time complexity of marginalization in graphical model G: O(D · 2^{tw(G)}).
- ► Exact marginalization in BN B with algebraic decision diagram as local factors: O(D|B|) = O(nD|S|).

Space complexity reduction:

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Efficient Marginalization

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- Exact marginalization in SPN S: O(D|S|).

Space complexity reduction:

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Space complexity reduction:

▶ No posterior over **h** to approximate anymore.

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Efficient Marginalization

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- ► Time complexity of marginalization in graphical model G: O(D · 2^{tw(G)}).
- ► Exact marginalization in BN B with algebraic decision diagram as local factors: O(D|B|) = O(nD|S|).
- Exact marginalization in SPN S: O(D|S|).

Space complexity reduction:

- ▶ No posterior over **h** to approximate anymore.
- ▶ No variational variables over **h** needed: $O(D|S|) \Rightarrow O(|S|)$.

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Logarithmic Transformation

New optimization objective:

$$\mathsf{maximize}_{q \in Q} \quad \mathbb{E}_{q(\mathbf{w})}[\log \sum_{\mathbf{h}} p(\mathbf{w}, \mathbf{h}, \mathbf{x})] + \mathbb{H}[q(\mathbf{w})]$$

which is equivalent to

minimize_{$q \in Q$} KL[$q(\mathbf{w}) \parallel p(\mathbf{w})$] - $\mathbb{E}_{q(\mathbf{w})}[\log p(\mathbf{x} \mid \mathbf{w})]$

- ▶ $p(\mathbf{w})$ prior distribution over \mathbf{w} , product of Dirichlets.
- ▶ $q(\mathbf{w})$ variational posterior over \mathbf{w} , product of Dirichlets.
- ▶ p(x | w) likelihood, not multinomial anymore after marginalization.

Non-conjugate $q(\mathbf{w})$ and $p(\mathbf{x} \mid \mathbf{w})$, no analytical solution for $\mathbb{E}_{q(\mathbf{w})}[\log p(\mathbf{x} \mid \mathbf{w})].$ Carnegie Mellon University

Logarithmic Transformation

Key observation:

$$p(\mathbf{x} \mid \mathbf{w}) = V_{\text{root}}(\mathbf{x} \mid \mathbf{w}) = \sum_{t=1}^{\tau_{S}} \prod_{(k,j) \in \mathcal{T}_{tE}} w_{kj} \prod_{i=1}^{n} p_t(X_i = \mathbf{x}_i)$$

is a posynomial function of **w**.

Make a bijective mapping (change of variable): $\mathbf{w}' = \log(\mathbf{w})$.

- Dates back to the literature of geometric programming.
- ► The new objective after transformation is convex in **w**'.

$$\log p(\mathbf{x} \mid \mathbf{w}) = \log \left(\sum_{t=1}^{\tau_{\mathcal{S}}} \exp \left(c_t + \sum_{(k,j) \in \mathcal{T}_{tE}} w'_{kj} \right) \right)$$

Jensen's inequality to obtain further lower bound.

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Logarithmic Transformation

Further lower bound:

 $\mathbb{E}_{q(\mathbf{w})}[\log p(\mathbf{x} \mid \mathbf{w})] = \mathbb{E}_{q(\mathbf{w}')}[\log p(\mathbf{x} \mid \mathbf{w}')] \geq \log p(\mathbf{x} \mid \mathbb{E}_{q'(\mathbf{w}')}[\mathbf{w}'])$

Relaxed objective:

$$\underset{\mathsf{Regularity}}{\mathsf{minimize}_{q \in Q}} \underbrace{\mathsf{KL}[q(\mathbf{w}) \mid\mid p(\mathbf{w})]}_{\mathsf{Regularity}} \underbrace{-\log p(\mathbf{x} \mid \mathbb{E}_{q'(\mathbf{w}')}[\mathbf{w}'])}_{\mathsf{Data fitting}}$$

Roughly, $\log p(\mathbf{x} | \mathbb{E}_{q'(\mathbf{w}')}[\mathbf{w}'])$ corresponds the log-likelihood by setting the weights of SPN as the posterior mean of $q(\mathbf{w})$.

Optimized by projected GD.

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Algorithm

Algorithm 1 CVB-SPN **Input:** Initial β , prior hyperparameter α , training instances $\{\mathbf{x}_d\}_{d=1}^D$. **Output:** Locally optimal β^* . 1: while not converged do Update $\mathbf{w} = \exp(\mathbb{E}_{q'(\mathbf{w}'|\boldsymbol{\beta})}[\mathbf{w}'])$ with Eq. 10. 2: Set $\nabla_{\boldsymbol{\beta}} = 0$. 3: for d = 1 to D do 4: 5: Bottom-up evaluation of $\log p(\mathbf{x}_d | \mathbf{w})$. Top-down differentiation of $\frac{\partial}{\partial \mathbf{w}} \log p(\mathbf{x}_d | \mathbf{w})$. 6: 7: Update $\nabla_{\boldsymbol{\beta}}$ based on \mathbf{x}_d . end for 8: Update $\nabla_{\boldsymbol{\beta}}$ based on $\mathbb{KL}(q(\mathbf{w}|\boldsymbol{\beta}) \parallel p(\mathbf{w}|\boldsymbol{\alpha}))$. 9: Update β with projected GD. 10: 11: end while

- Line 4 8 easily parallelizable, distributed version.
- ► Sample minibatch in Line 4 8, stochastic version.

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Experiments

- Experiments on 20 data sets, report average log-likelihoods, Wilcoxon ranked test.
- Compared with (O)MLE-SPN and OBMM-SPN.



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Experiments



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Thanks Q & A

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